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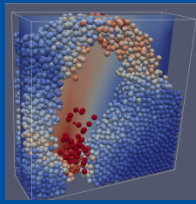
LIGGGHTS OPEN SOURCE DEM: COUPLING TO DNS OF TURBULENT CHANNEL FLOW

6th ERCOFTAC SIG43 Workshop, Udine, October 2013

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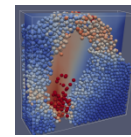


I. The LIGGGHTS Code

An Introduction

Motivation and Background

The Importance of Bulk Solids



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A definition of bulk solids*:

A bulk solid (granular material) consists of many particles (granules) of different sizes (and possibly different chemical compositions, densities, shapes) randomly grouped together to form a bulk. The “nature” of such a material (...) is thus dependent on many factors (...).“

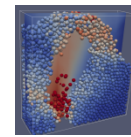


photo from: Whiddon, P.: <http://www.flickr.com/photos/pwhiddon/>

* Woodcock, C. R., Mason, J. S. (1987): Bulk Solids Handling: An Introduction To The Practice And Technology, Technology & Engineering.

Motivation and Background

The Importance of Bulk Solids



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The Importance of Bulk Solid Handling:

- **More than 50% of all products** sold are either granular in form or involve granular materials in their production.*
- **About 40% of the value added in chemical industry** is linked to particle technology.**
- Despite this importance, the **mechanics** of granular materials is **not well understood at present**.***



photo from: Whiddon, P.: <http://www.flickr.com/photos/pwhiddon/>

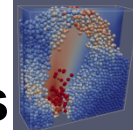
* Bates, L. (2006): The need for industrial education in bulk technology", Bulk Solids Handl., 26, 464-473.

** Ennis, B. J., Green, J., Davies, R.(1994): Particle technology.The legacy of neglect in the US", Chem. Eng. Prog, 90, 32-43.

*** Campbell, C. S. (2006): Granular Material Flows - An Overview", Powder Technology, 162, 208-229.

Motivation and Background

Examples of Granular Materials



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Geomechanics, Construction: Sand, gravel, stone, asphalt

Mining and Mineral Processing, Metals: Coal, Ores of all kinds

Agricultural Machinery: Crops of all kinds, sugar, flour, fruits, wood pellets

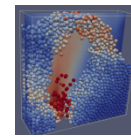
Pharmacy: Tablets (pills), powders

Chemical industry: Chemical powders and bulk materials, plastic pellets

Consumer goods: “PEZ”, bonbons, cosmetic powder, detergent, cornflakes,...

Motivation and Background

Discrete Element Method



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- DEM manages information about **each individual particle** (mass, velocity, ...)
and the forces acting on it.
- Each particle is tracked in **Lagrangian Frame**, the force balance

$$m_p \ddot{\vec{x}}_p = \sum_i \vec{F}_i$$

is integrated using an appropriate integration scheme.

- DEM can take into account the particle's shape

Examples of forces $\vec{F}_i$ that can be included:

- Contact forces (particle-particle, particle-wall)
- Gravity
- Fluid drag force

Soft sphere approach (Classical DEM, constant time-stepping)

$$m_p \ddot{\vec{x}}_p = \vec{F}_n + \vec{F}_t + m\vec{g}$$

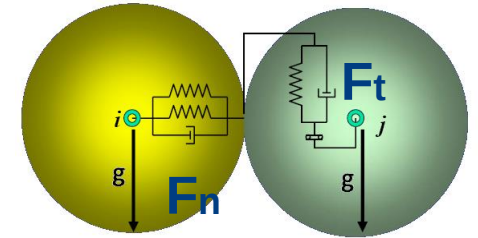
A **small overlap δ between particles** is allowed
 The **normal force** tending to repulse the particles is

$$\vec{F}_n = -k_n \vec{\delta} + c_n \vec{\Delta v}_n$$

δ : spatial overlap, Δv_n : normal relative velocity at the contact point.
 The **tangential force** F_t (representing elastic tangential deformation) can be written as

$$\vec{F}_t = k_t \underbrace{\left| \int_{t_{c,0}}^t \Delta \vec{v}_t(\tau) d\tau \right|}_{\text{"}\delta_t\text{"}} \vec{t} + c_t \vec{\Delta v}_t, \quad \max\left(\left| \vec{F}_t \right| \right) = \left| \mu \vec{F}_n \right|$$

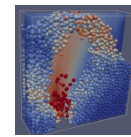
Δv_t : relative tangential velocity, t : contact point tangential vector
 $t_{c,0}$: time when the contact between the particles started



A simple soft-sphere
 contact model:
 Linear spring-dashpot

The LIGGGHTS Code

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- **LIGGGHTS** = An Open Source, C++, MPI parallel DEM code
- **L**AMMPS **I**MPROVED FOR **G**ENERAL **G**RANULAR AND **G**RANULAR
- **H**EAT **T**RANSFER **S**IMULATIONS
- WWW.LIGGGHTS.COM | WWW.CFDEM.COM
- Based on the popular MD code **LAMMPS** (Sandia National Labs, USA)
- **LAMMPS** = **L**arge-Scale **A**tomic/**M**olecular **M**assively **P**arallel **S**imulator
A **massively parallel, widely used, C++, Open Source MD code**
More generally, it is a **parallel particle simulator**
- **CFDEM**: Coupling to CFD code OpenFOAM®

The LIGGGHTS Code

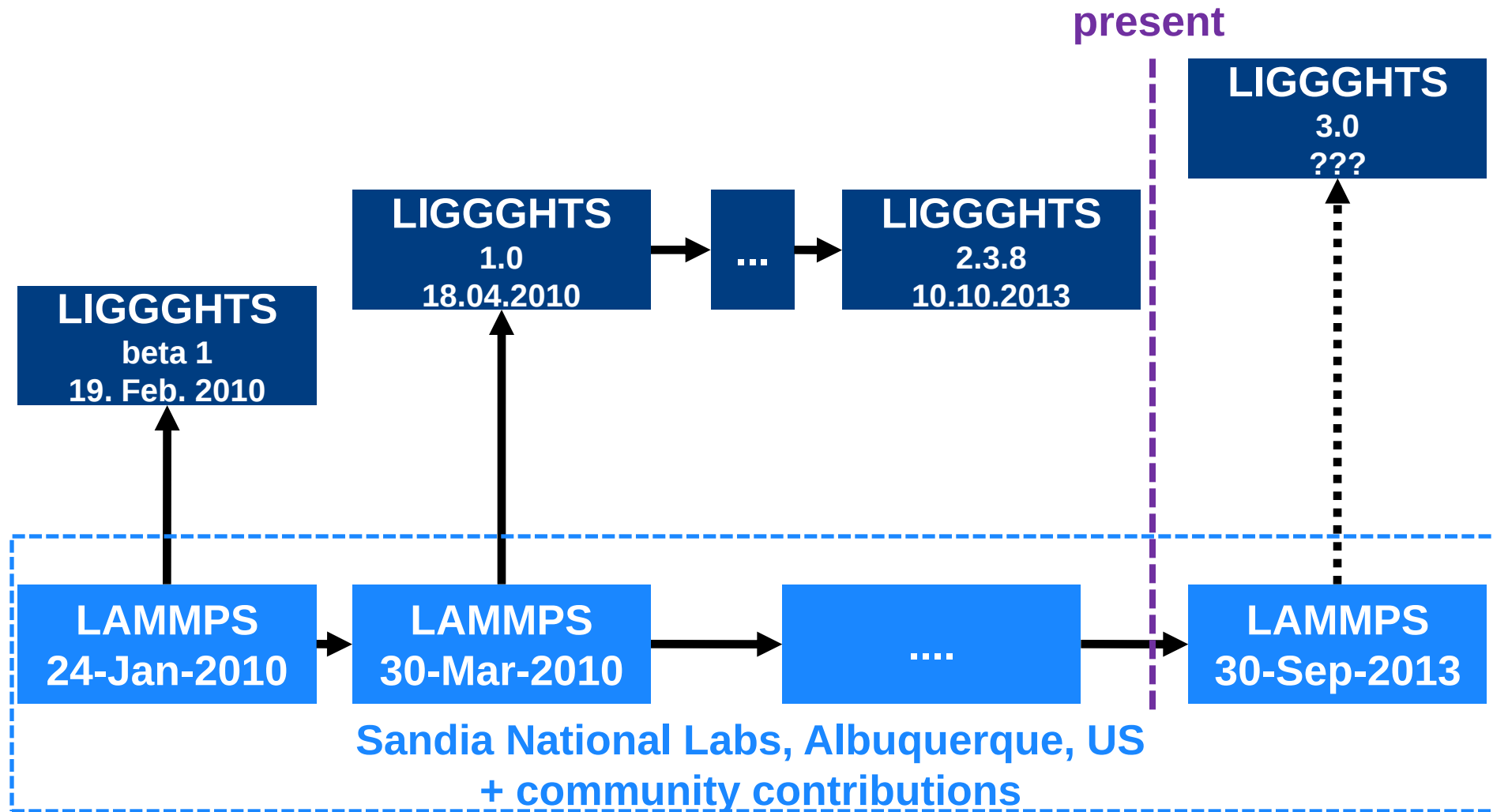
The LAMMPS Code

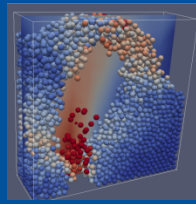


- **LAMMPS = Large-Scale Atomic and Molecular Massively Parallel Simulator**
- **OpenSource MD code under GPL**, provided by **Sandia National Laboratories** since the mid 90's (<http://lammps.sandia.gov/>). **Widely used** (over **500 journal publications** 2000-2009 using LAMMPS, <http://lammps.sandia.gov/papers.html>)
- LAMMPS has potentials for soft materials (biomolecules, polymers), solid-state materials (metals, semiconductors) and **coarse-grained systems**. It can be used to model atoms or, more generically, as a **parallel particle simulator** at the atomic, meso, or continuum scale.
- LAMMPS is a **C++** code, it runs on single processors or in parallel using **message-passing** techniques and a **spatial-decomposition of the simulation domain**.
- It is **fast and efficient** and also used on huge clusters (e.g. on Sandia Red Storm with 16k Quadcore nodes, simulations with billions of particles performed)
- **GPU / CUDA** acceleration packages for NVIDIA hardware

The LIGGGHTS Code

Relation to LAMMPS





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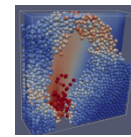


II. LIGGGHTS Features and Models

An Overview

The LIGGGHTS Code

Feature Overview



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Features added to LAMMPS

**Hertz / Hooke pair styles w/ shear history
incl. closure contact law to material params**

Particle insertion improved

Mesh import from CAD (for walls)

Moving mesh

Multisphere method

Macroscopic cohesion model

Heat transfer model

Particle bonds with torques

Wall stress analysis

6 dof solver

Dynamic Load Balancing

The LIGGGHTS Code

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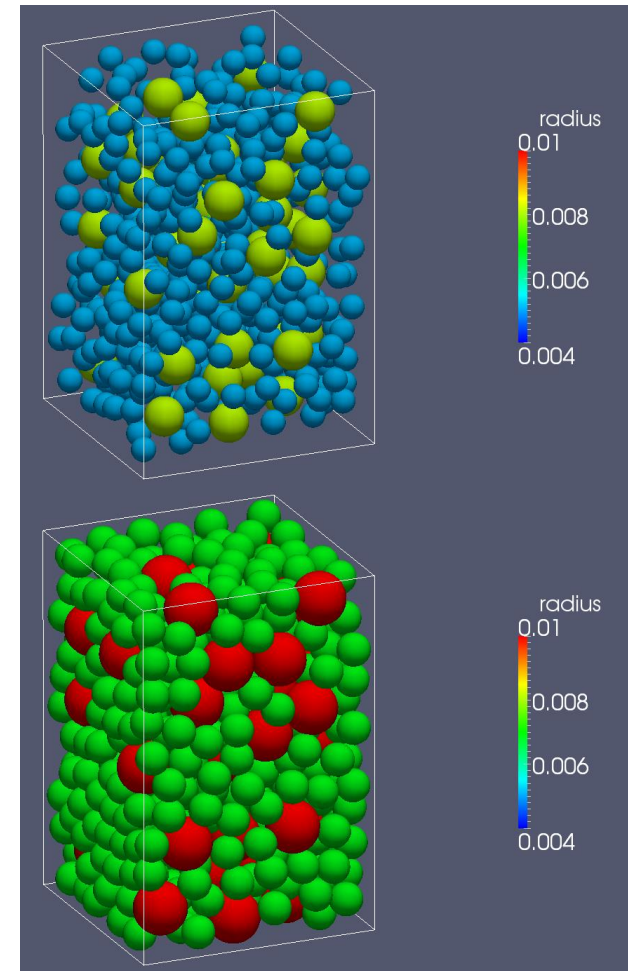
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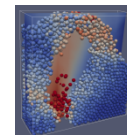
Dynamic Load Balancing



Packing by particle growth

The LIGGGHTS Code

Feature Overview



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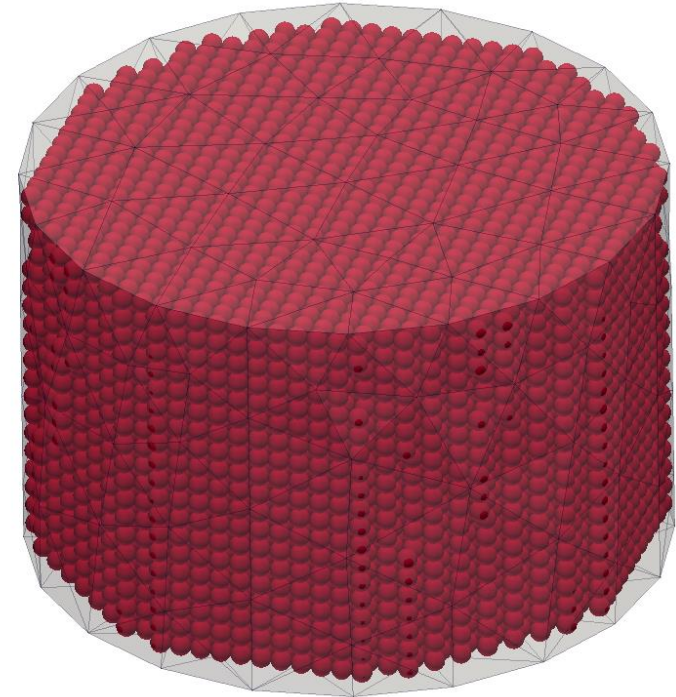
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Packing in tetrahedral mesh

The LIGGGHTS Code

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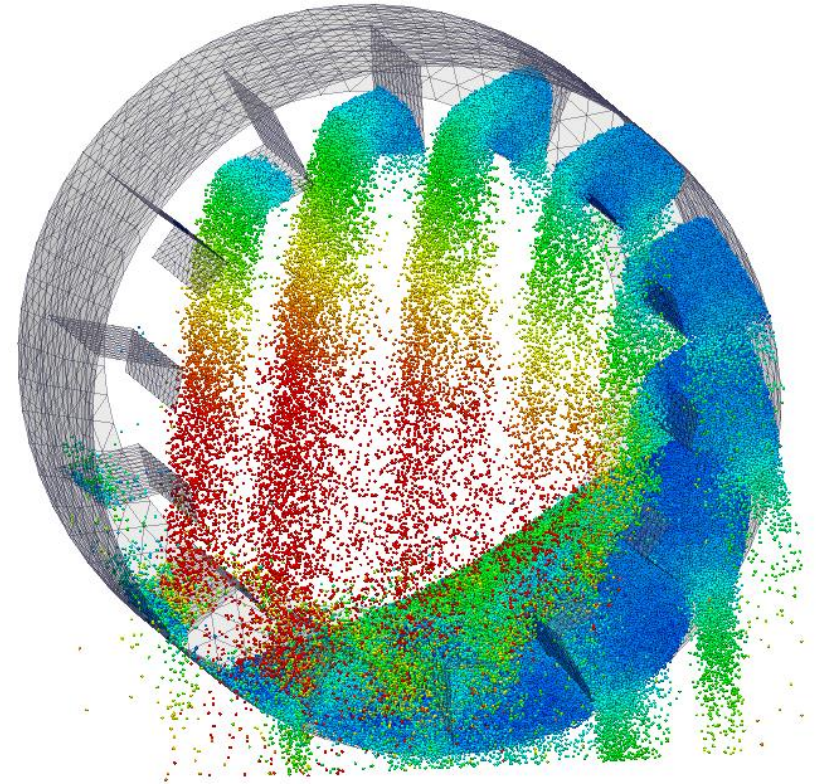
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**Simulation of a rotary dryer
~1.000.000 particles**

The LIGGGHTS Code

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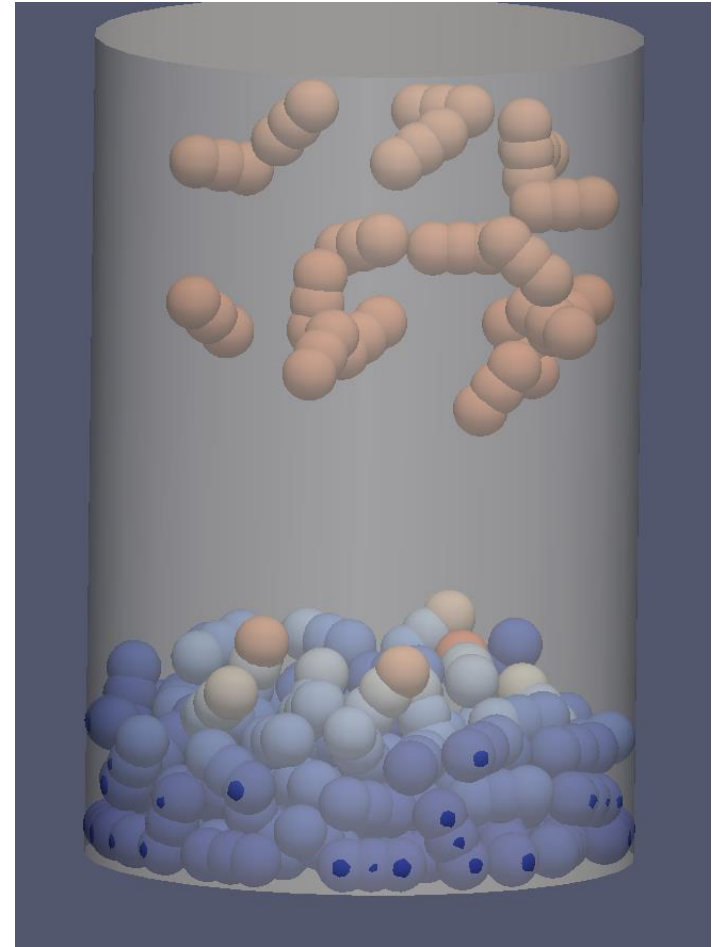
Heat transfer model

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**Each body is described by center of mass,
mass and inertia tensor.**

The LIGGGHTS Code

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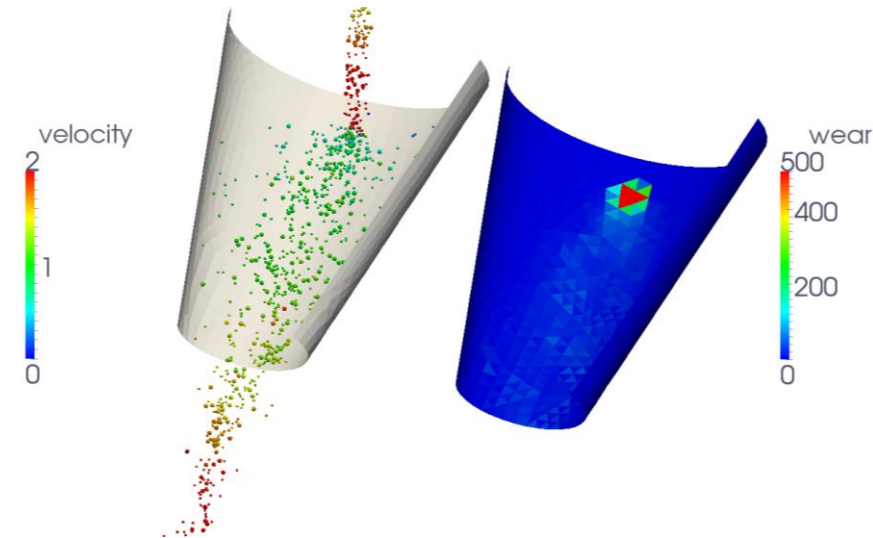
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**Wear prediction
(Finnie model)**

The LIGGGHTS Code

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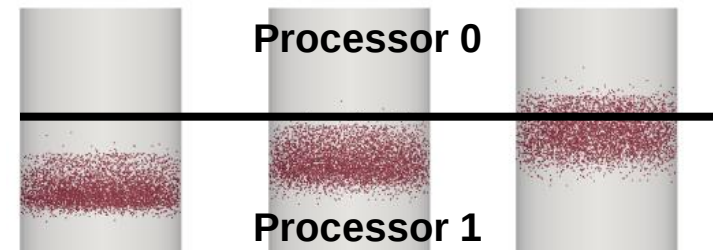
Wall stress analysis

6 dof solver

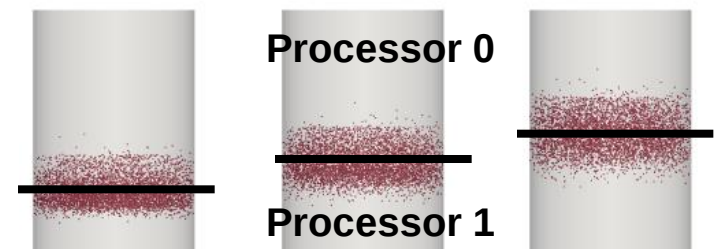
Dynamic Load Balancing

How to distribute load between processors?

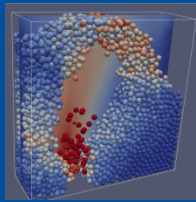
Without dynamic load balancing:



With dynamic load balancing:



advancing simulation time



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III. DNS + LIGGGHTS

One-Way Coupling

Establish A One-Way Coupling Coupling to LIGGGHTS



LIGGGHTS already designed to allow it to be coupled to other codes.

At least 3 ways to handle coupling

- **LIGGGHTS is the driver code** (other code is called during time-stepping)
- **LIGGGHTS and the other code are** on a more **equal** footing (other code is called every few time steps)
- **Use LIGGGHTS as a library** called by another code.

Establish A One-Way Coupling Tasks (Spherical Particles)



Direct Numerical Simulation gives

- **fluid velocity field** in spectral space (in terms of Fourier/Chebyshev coefficients)

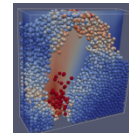
LIGGGHTS

- **read data** from DNS
- **transform data** into velocity field in physical space
- **interpolate data** at particle position using Lagrange polynomials
- **apply Schiller-Naumann drag force to spherical particles***

$$\frac{F}{\rho_f U^2 A} = \frac{12}{\text{Re}} (1 + 0.15 \text{Re}^{0.687}) .$$

* L. Schiller and A. Naumann, Fundamental calculations in gravitational processing. Zeitschrift des Vereines Deutscher Ingenieure, 77(12), 318-320 (1933).

Establish A One-Way Coupling Tasks (Ellipsoidal Particles)



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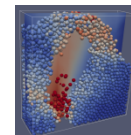
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- **modify force** to take into account particle shape
- **apply torque** according to Euler equations

Results

Spherical Particles

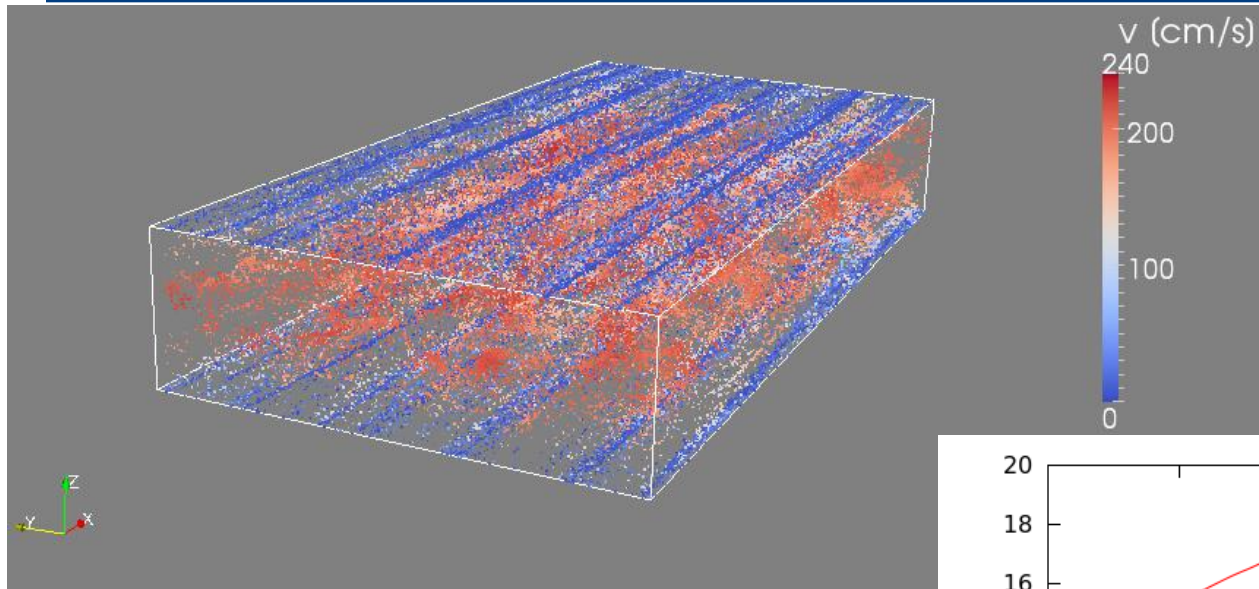


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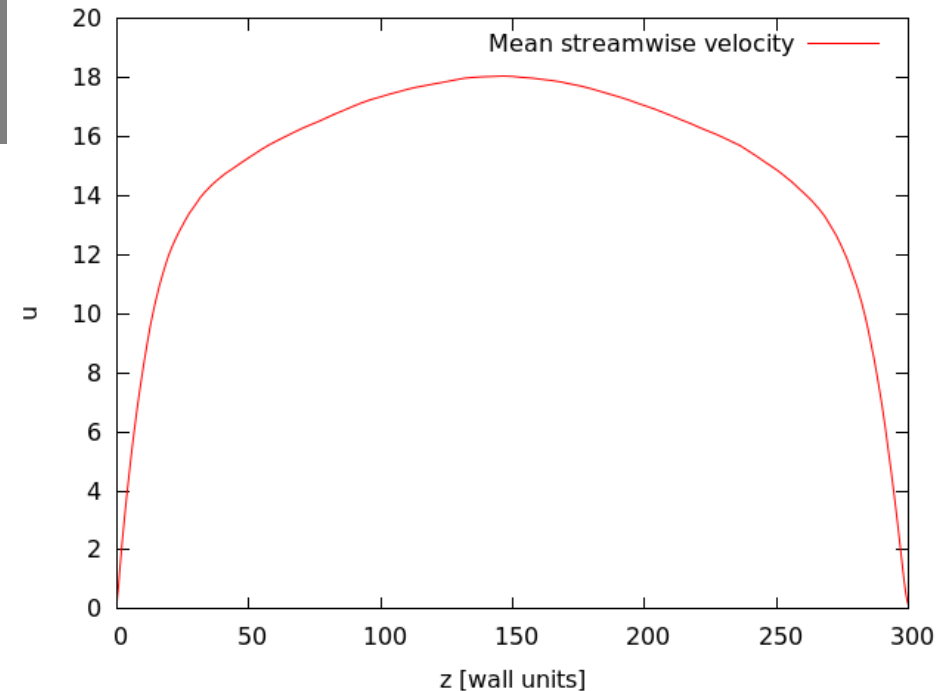
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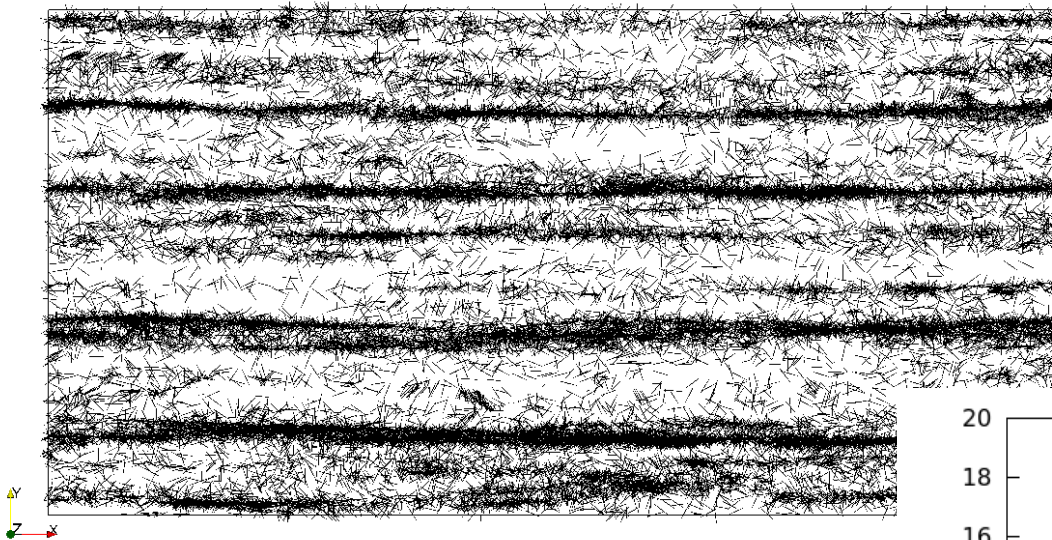


100.000 particles in simulation
6000 DNS output files read
(~1 s of simulated time)



Results

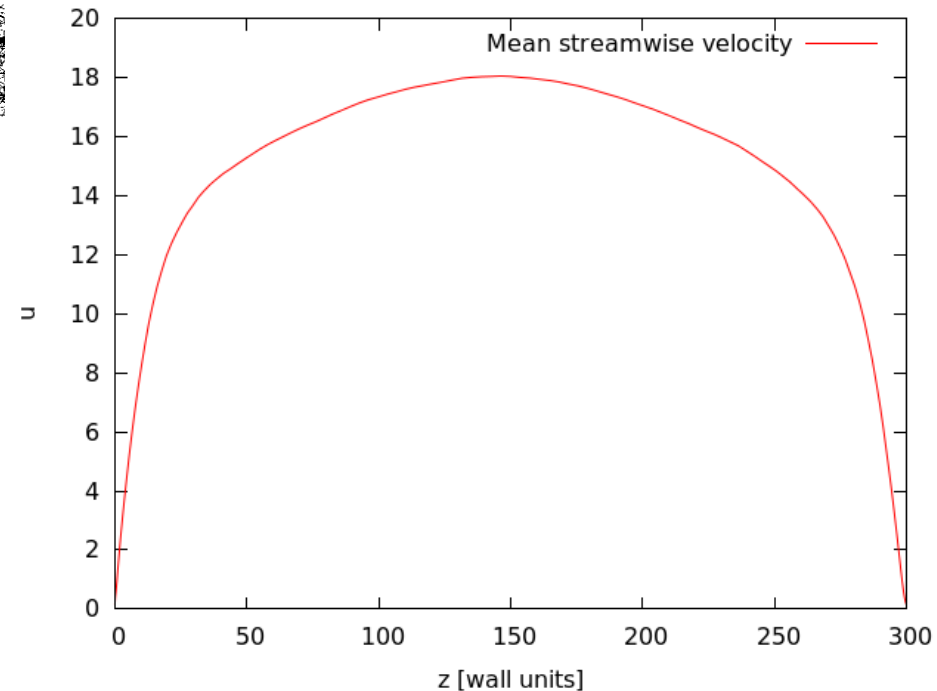
Ellipsoidal Particles



100.000 particles in simulation ($b/a = 50$)

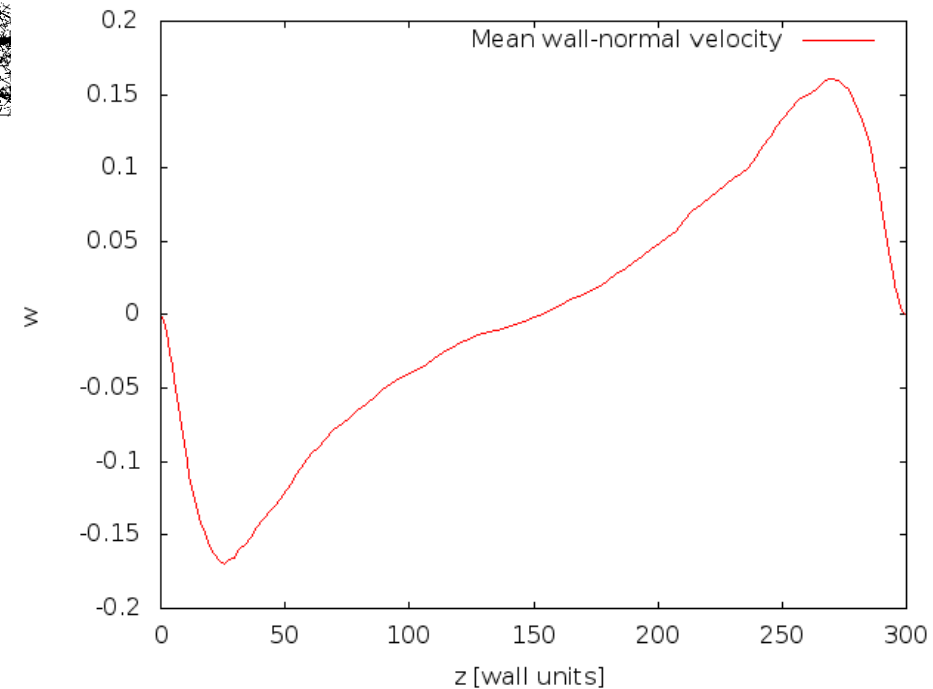
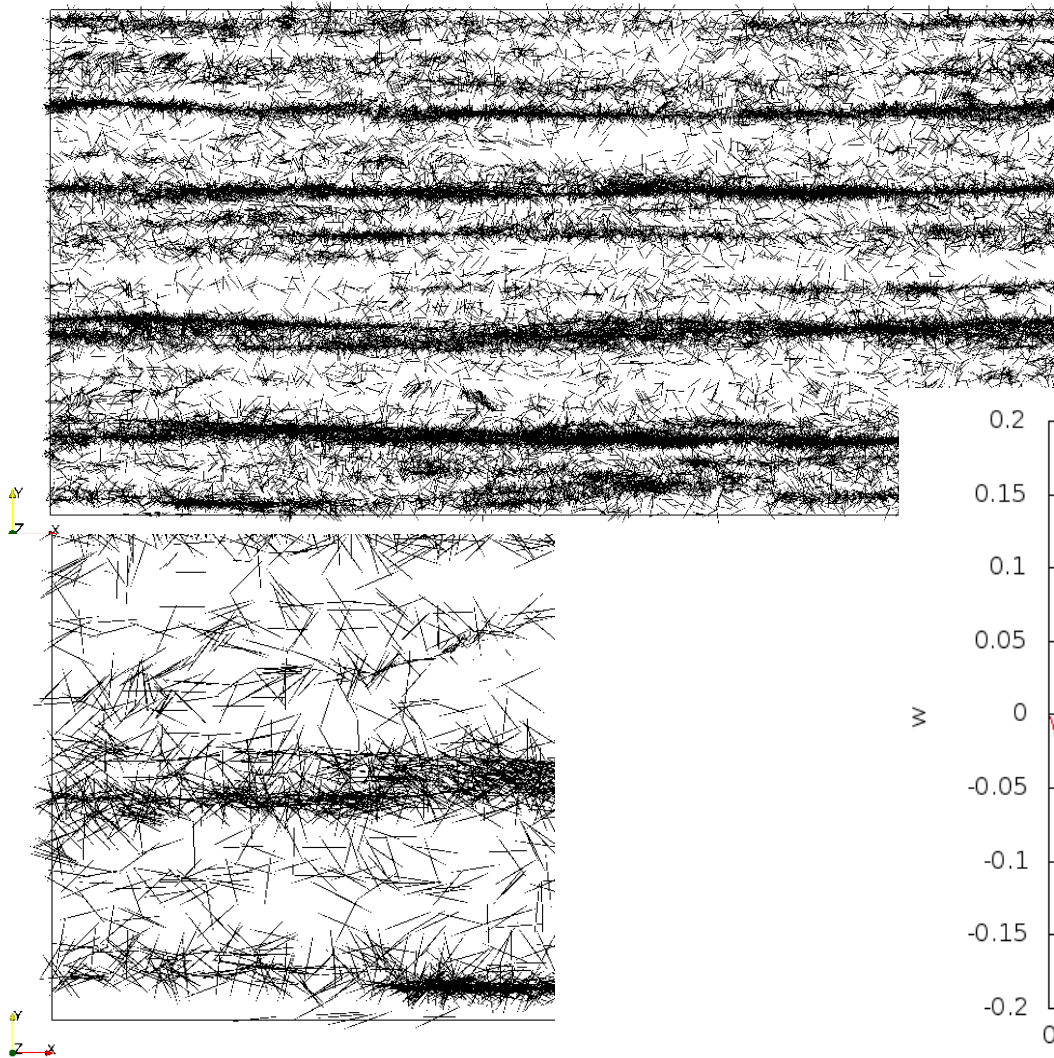
6000 DNS output files read

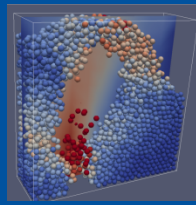
(~1 s of simulated time)



Results

Ellipsoidal Particles





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Thank you for your attention!
Questions?

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