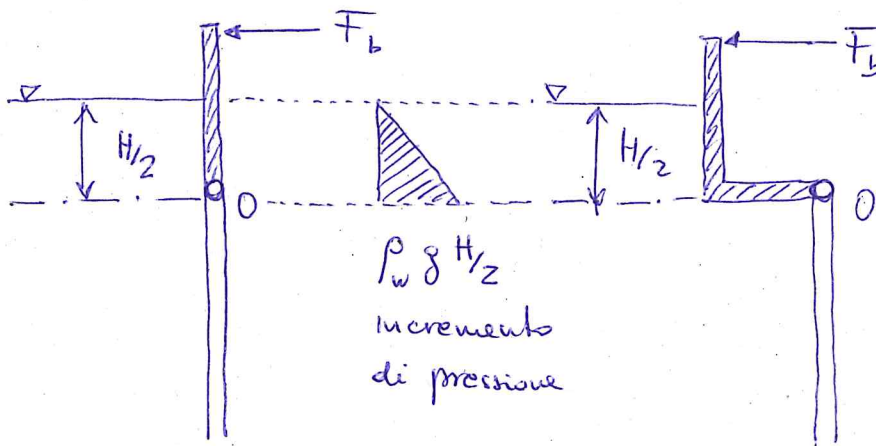


CONFIG. A :

CONFIG. B :



1.1) Calcolo di F_b per configurazione A :

Momento generato dall'acqua sul lato sx della paratia :

$$M_w = F_w \cdot b$$

$$\text{con } F_w = \rho_w g H/2 \cdot H/2 \cdot \frac{1}{2} W = \frac{1}{8} \rho_w g H^2 \cdot W$$

$$b = \frac{1}{3} \cdot \frac{H}{2} = \frac{H}{6}$$

$$M_w = \frac{1}{96} \rho_w g H^3 W$$

[5%]

Momento generato dalla forza F_b sul lato dx della paratia :

$$M_b = F_b \cdot b' \quad [2\%]$$

$$\text{con } b' = H$$

Desidero risultare $M_w = M_b$ si ottiene :

$$[3\%] \quad F_b = \frac{M_w}{b'} = \frac{1}{96} \rho_w g H^2 \cdot W \quad [10\%]$$

1.2) Calcolo di F_b per configurazione B:

L2

Momento generato dall'acqua sul lato sx della piastra:

$$M_w = F_w^{or} \cdot b' + F_w^{ver} \cdot b''$$

$$\text{con } F_w^{or} = \frac{1}{8} \rho_w g H^2 \cdot W \quad ; \quad b' = \frac{H}{6} \quad [2\%]$$

$$F_w^{ver} = \rho_w g \frac{H}{2} \cdot L W \quad ; \quad b'' = \frac{L}{2} \quad [6\%]$$

$$M_w = \frac{1}{48} \rho_w g H^3 \cdot W + \frac{1}{4} \rho_w g H L^2 \cdot W$$

Momento generato dalle forze F_b sul lato dx:

$$M_b = F_b \cdot H \quad [3\%]$$

Dalla condizione $M_w = M_b$

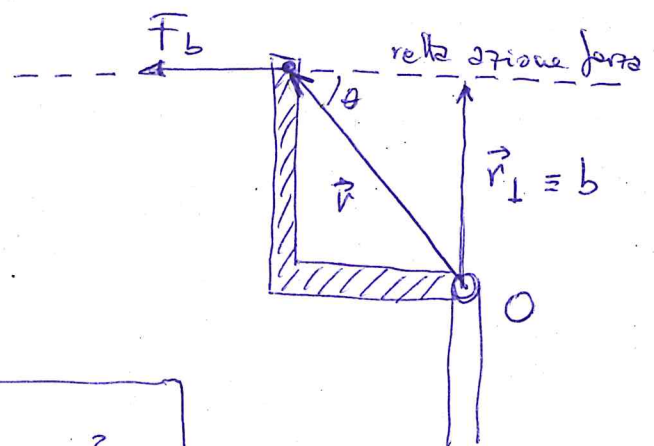
si ricava:

$$F_b = \frac{1}{48} \rho_w g H^2 \cdot W + \frac{1}{4} \rho_w g \cdot L^2 W$$

[4%]

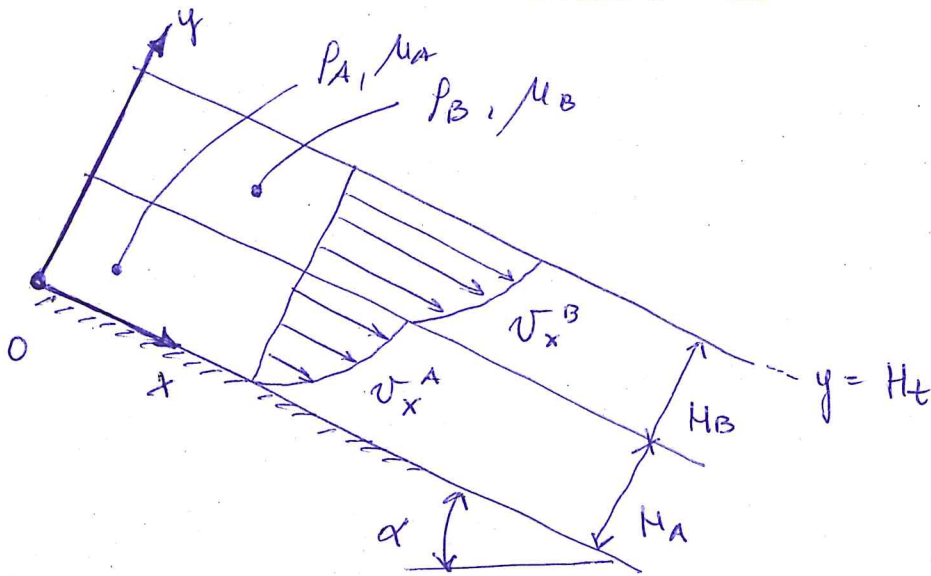
$$= \frac{1}{4} \rho_w g \cdot W \left(\frac{H^2}{12} + L^2 \right)$$

[15%]



EXE 2

11



$$\frac{\partial P}{\partial x} = \frac{dP}{dx} = -\rho g \sin \alpha$$

[4%]

$$p_A = p_B$$

$$\mu_A > \mu_B$$

↑
-4% se
non
calcolato

2.1) Calcolo dei profili di velocità

Eq. di conservazione semplificate:

$$\frac{\partial v_x}{\partial x} = 0 \quad [1\%]$$

$$0 = -\frac{\partial P}{\partial x} + \mu \frac{\partial^2 v_x}{\partial y^2} \quad \Rightarrow \quad \begin{cases} v_x^A = \frac{1}{2\mu_A} \left(\frac{dP}{dx} \right) y^2 + C_1 y + C_2 \\ v_x^B = \frac{1}{2\mu_B} \left(\frac{dP}{dx} \right) y^2 + C_3 y + C_4 \end{cases}$$

C.C. #1: $v_x^A (y=0) = 0 \quad \rightarrow \quad \boxed{C_2 = 0} \quad [2\%]$

C.C. #2: $\tau_{yx}^B (y=H_t) = 0 \quad ; \quad \mu_B \frac{\partial v_x^B}{\partial y} \Big|_{y=H_t} = 0$

$$\mu_B \left[\frac{1}{\mu_B} \left(\frac{dP}{dx} \right) y + C_3 \right] \Big|_{y=H_t} = 0$$

$$\boxed{C_3 = - \left(\frac{dP}{dx} \right) \cdot \frac{H_t}{\mu_B}} \quad [4\%]$$

$$C.C. \#3: \quad \Sigma_{yx}^A (y = H_A) = \Sigma_{yx}^B (y = H_A)$$

$$\mu_A \left. \frac{\partial U_x^A}{\partial y} \right|_{y=H_A} = \mu_B \left. \frac{\partial U_x^B}{\partial y} \right|_{y=H_A}$$

$$\mu_A \left[\frac{1}{\mu_A} \left(\frac{dP}{dx} \right) \cdot H_A + C_1 \right] = \mu_B \left[\frac{1}{\mu_B} \left(\frac{dP}{dx} \right) H_A + C_3 \right]$$

$$\mu_A \cdot C_1 = \mu_B \cdot C_3 \rightarrow \left[C_1 = \frac{\mu_B}{\mu_A} C_3 \right]$$

$$[3\%] = - \left(\frac{dP}{dx} \right) \cdot \frac{H_t}{\mu_A}$$

$$C.C. \#4: \quad U_x^A (y = H_A) = U_x^B (y = H_A)$$

$$\frac{1}{2\mu_A} \left(\frac{dP}{dx} \right) \cdot H_A^2 + C_1 \cdot H_A = \frac{1}{2\mu_B} \left(\frac{dP}{dx} \right) \cdot H_A^2 + C_3 \cdot H_A + C_4$$

$$\left[C_4 = \frac{1}{2} \left(\frac{dP}{dx} \right) H_A^2 \cdot \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) + (C_1 - C_3) \cdot H_A \right]$$

$$= \frac{1}{2} \left(\frac{dP}{dx} \right) H_A^2 \cdot \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) + H_A \left[- \left(\frac{dP}{dx} \right) \cdot \frac{H_t}{\mu_A} + \left(\frac{dP}{dx} \right) \cdot \frac{H_t}{\mu_B} \right]$$

$$= \frac{1}{2} \left(\frac{dP}{dx} \right) H_A^2 \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) - \left(\frac{dP}{dx} \right) \cdot H_t \cdot \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) H_A$$

$$= \left(\frac{dP}{dx} \right) \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) \cdot \left(\frac{H_A^2}{2} - H_t \cdot H_A \right) \quad [1] [6\%]$$

o anche:

$$C_4 = \left(\frac{dP}{dx} \right) \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) H_A \left(\frac{1}{2} H_A + H_B \right) \quad [2]$$

Le espressioni [1] e [2] sono equivalenti.

Pertanto risulta:

$$V_x^A = \frac{1}{2\mu_A} \left(\frac{dP}{dx} \right) (y^2 - 2H_t \cdot y) \quad [3\%]$$

$\underbrace{\hspace{10em}}_{-\rho g \sin \alpha}$

$$V_x^B = \frac{1}{2\mu_B} \left(\frac{dP}{dx} \right) (y^2 - 2H_t \cdot y) + \left(\frac{dP}{dx} \right) \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) \left(\frac{H_A^2}{2} - H_t \cdot H_A \right) \quad [5\%]$$

CONTROLO (NON RICHIESTO):

$$V_x^A (y = H_A) = \frac{1}{2\mu_A} \left(\frac{dP}{dx} \right) (H_A^2 - 2H_t \cdot H_A)$$

$$V_x^B (y = H_A) = \frac{1}{2\mu_B} \left(\frac{dP}{dx} \right) (H_A^2 - 2H_t \cdot H_A) +$$

$$\left| + \left(\frac{dP}{dx} \right) \left(\frac{1}{\mu_A} - \frac{1}{\mu_B} \right) \frac{1}{2} (H_A^2 - 2H_t \cdot H_A) \right.$$
$$= \frac{1}{2\mu_A} \left(\frac{dP}{dx} \right) (H_A^2 - 2H_t \cdot H_A) \quad \checkmark$$

2.2) Calcolo della portata volumetrica Q/W

4

per $H_A = H_B = H$ e $\mu_A = 2\mu_B = 2\mu$:

$$v_x^A = \frac{1}{4\mu} \left(\frac{dP}{dx} \right) (y^2 - 4Hy) \quad [1\%]$$

$$\begin{aligned} v_x^B &= \frac{1}{2\mu} \left(\frac{dP}{dx} \right) (y^2 - 4Hy) + \\ &+ \left(\frac{1}{2\mu} - \frac{1}{\mu} \right) \left(\frac{dP}{dx} \right) \left(\frac{H^2}{2} - 2H^2 \right) \\ &= \frac{1}{2\mu} \left(\frac{dP}{dx} \right) (y^2 - 4Hy) + \frac{1}{2\mu} \left(\frac{dP}{dx} \right) \cdot \frac{3}{2} H^2 \quad [1\%] \end{aligned}$$

$$\begin{aligned} \frac{Q_A}{W} &= \int_0^H v_x^A dy = \frac{1}{4\mu} \left(\frac{dP}{dx} \right) \int_0^H (y^2 - 4Hy) dy \\ &= \frac{1}{4\mu} \left(-\frac{dP}{dx} \right) \cdot \frac{5}{3} H^3 \\ &= \left(\frac{y^3}{3} - 4H \cdot \frac{y^2}{2} \right) \Big|_0^H = \\ &= \frac{H^3}{3} - 2H^3 = -\frac{5}{3} H^3 \end{aligned}$$

$$\boxed{\frac{Q_A}{W} = \frac{5}{12\mu} \left(-\frac{dP}{dx} \right) H^3} \quad [3\%]$$

$$\frac{Q_B}{W} = \int_H^{2H} v_x^B dy = \frac{1}{2\mu} \left(\frac{dP}{dx} \right) \int_H^{2H} (y^2 - 4Hy) dy + \frac{1}{2\mu} \left(\frac{dP}{dx} \right) \cdot \frac{3}{2} H^2 \int_H^{2H} dy$$

$$= \frac{1}{2\mu} \left(\frac{dP}{dx} \right) \cdot \left(\frac{y^3}{3} - 2Hy^2 \right) \Big|_H^{2H} + \frac{3}{4\mu} \left(\frac{dP}{dx} \right) H^3$$

$$\frac{8}{3} H^3 - \frac{H^3}{3} - 8H^3 + 2H^3 =$$

$$\frac{7}{3} H^3 - 6H^3 = -\frac{11}{3} H^3$$

$$= \frac{11}{6\mu} \left(-\frac{dP}{dx} \right) H^3 + \frac{3}{4\mu} \left(\frac{dP}{dx} \right) H^3 \quad \left[\frac{11}{6} - \frac{3}{4} = \frac{26}{24} \right]$$

$$= \frac{13}{12\mu} \left(-\frac{dP}{dx} \right) H^3$$

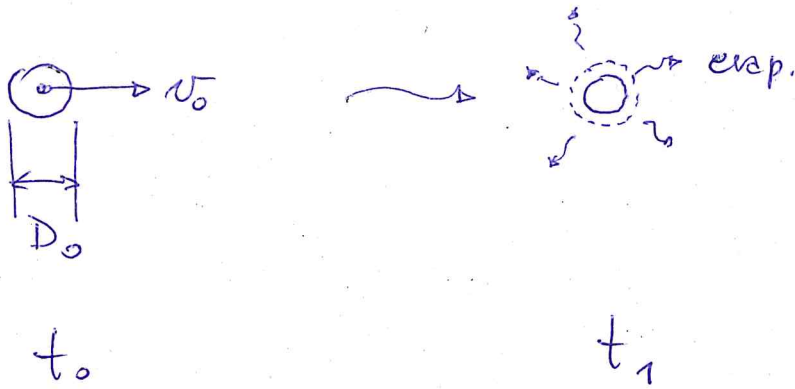
$$\boxed{\frac{Q_B}{W} = \frac{13}{12\mu} \left(-\frac{dP}{dx} \right) H^3} \quad [4\%]$$

$$\frac{Q_{TOT}}{W} = \frac{Q_A}{W} + \frac{Q_B}{W} = \frac{3}{2\mu} \left(-\frac{dP}{dx} \right) H^3 \quad [1\%]$$

Je fais
la somme

11

EXE 3



3.1) Calcolo di $D_p(t)$:

$$\frac{dM_p}{dt} = \frac{d}{dt} \left(\rho_p \frac{\pi D_p^3}{6} \right) = \rho_p \frac{\pi}{2} \cdot D_p^2 \frac{dD_p}{dt} \quad [1\%]$$

$$\frac{dM_p}{dt} = -c \quad \text{dal bilancio di masse} \quad [1\%]$$

Risultato : $-\cancel{k} \pi \cancel{D_p^2} = \rho_p \frac{\pi}{2} D_p^2 \frac{dD_p}{dt}$

$$\frac{dD_p}{dt} = -\frac{2k}{\rho_p} \quad [1\%]$$

$$\int_{D_0}^{D_p(t)} dD_p = -\frac{2k}{\rho_p} \int_0^t dt$$

[2%] $D_p(t) = D_0 - \frac{2k}{\rho_p} t$ [5%]

3.2) Calcolo di t^* tale che $D_p(t) = D_0/3$:

$$D_p(t^*) = \frac{D_0}{3} = D_0 - \frac{2k}{\rho_p} \cdot t^*$$

$$t^* = \frac{1}{3} \cdot \frac{\rho_p \cdot D_0}{k} \quad [5\%]$$

Controllo dimensionale : $\left[\frac{\text{kg}}{\text{m}^3} \cdot \text{m} \cdot \frac{\text{m}^2 \cdot \text{s}}{\text{kg}} \right] \checkmark$

3.3) Calcolo di $v_p(t)$:

$$m_p \frac{dv_p}{dt} + v_p \frac{dm_p}{dt} = -3\pi \mu v_p D_p \quad \left. \begin{array}{l} \vec{u}_f = \vec{0} \\ C_D = 24/Re_p \end{array} \right\} [3\%]$$

$$\frac{dv_p}{dt} = - \frac{18\mu}{\rho_p D_p^2} v_p + \frac{6k}{\rho_p D_p} \cdot v_p \quad [3\%]$$

$$\frac{dv_p}{v_p} = \left(- \frac{18\mu}{\rho_p} \cdot \frac{1}{D_p^2} + \frac{6k}{\rho_p} \cdot \frac{1}{D_p} \right) dt$$

$$= \left(+ \frac{9\mu}{k} \cdot \frac{1}{D_p^2} - 3 \cdot \frac{1}{D_p} \right) dD_p \quad [4\%]$$

\uparrow
 $dt = - \frac{\rho_p}{2k} dD_p$

Integrando si ottiene :

$$\ln v_p \Big|_{v_0}^{v_p(t)} = \frac{9\mu}{k} \left(- \frac{1}{D_p} \right) \Big|_{D_0}^{D_p(t)} - 3 \ln D_p \Big|_{D_0}^{D_p(t)} \quad [4\%]$$

$$\ln \left[\frac{V_p(t)}{V_0} \right] = \ln \left[\frac{D_p(t)}{D_0} \right]^{-3} + \frac{3\mu}{k} \left(\frac{1}{D_0} - \frac{1}{D_p(t)} \right) \quad [3\%]$$

Elevando tutto all' esponente:

$$V_p(t) = V_0 \left(\frac{D_0}{D_p(t)} \right)^3 \cdot e^{\frac{3\mu}{k} \left(\frac{1}{D_0} - \frac{1}{D_p(t)} \right)} \quad [3\%]$$

con $D_p(t) = D_0 - \frac{2k}{\rho_p} \cdot t$ [20%]

3.4) Calcolo di $V_p(t^*)$:

$$V_p(t^*) = V_0 \left(\frac{D_0}{D_p(t^*)} \right)^3 \cdot e^{\frac{3\mu}{k} \left(\frac{1}{D_0} - \frac{1}{D_p(t^*)} \right)}$$

$\underbrace{\frac{D_0}{D_p(t^*)}}_{\substack{= 3 \\ (D_0/3)}}$

$\underbrace{\frac{1}{D_0} - \frac{3}{D_0}}_{= -\frac{2}{D_0}}$

$$= V_0 (3)^3 \cdot e^{\frac{3\mu}{k} \cdot \left(-\frac{2}{D_0}\right)}$$

$V_p(t) = 27V_0 \cdot e^{-\frac{18\mu}{kD_0}}$
[5%]

Controllo dimensionale: $\frac{\mu}{kD_0} = \frac{kg}{m \cdot s} \cdot \frac{m^2/s}{kg} \cdot \frac{1}{m} \quad \checkmark$