

# PARTICLE TRACKING IN A CELLULAR FLOW FIELD

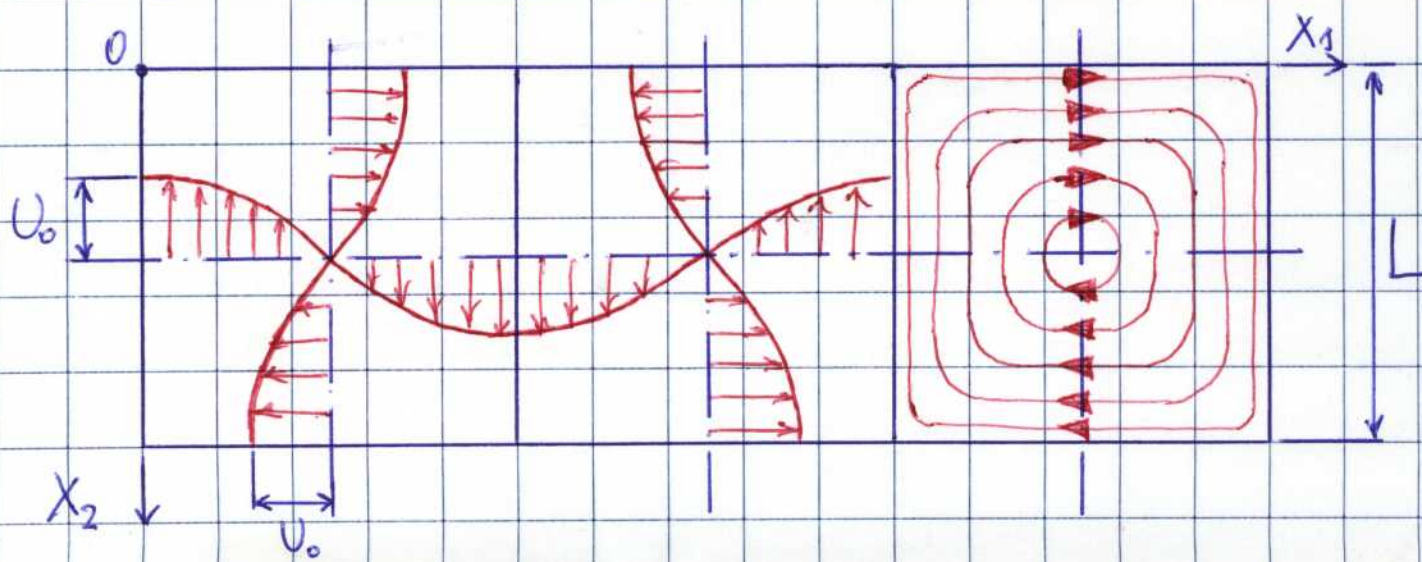
Objective : simulate numerically the dispersion of small particles in a simplified turbulent flow field

## (A) FLOW FIELD

2D periodic flow of cellular vortices

Incompressible

$$\psi = U_0 L \sin(x_1/L) \sin(x_2/L)$$



# Fluid velocity components :

$$u_1 = \frac{dX_1}{dt} = U_0 \sin(X_1/L) \cos(X_2/L)$$

$$u_2 = \frac{dX_2}{dt} = -U_0 \cos(X_1/L) \sin(X_2/L)$$

## (B) PARTICLE MOTION EQUATIONS

Start from Maxey & Riley (1983):

$$m_p \frac{d\vec{V}}{dt} = (m_p - m_f) \vec{g} + m_f \frac{D\vec{u}}{Dt} \Big|_{\vec{Y}(t)}$$

INERTIA

BUOYANCY

EFFECTS OF PRESSURE GRAD. OF THE UNDISTURBED FLOW

$$\frac{D\vec{u}}{Dt} = \frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla \vec{u}$$

$$\frac{d\vec{u}}{dt} = \frac{\partial \vec{u}}{\partial t} + \vec{v} \cdot \nabla \vec{u}$$

$$- \frac{1}{2} m_f \frac{d}{dt} \left[ \vec{V} - \vec{u} \Big|_{\vec{Y}(t)} \right] - 6\pi a \mu \left[ \vec{V} - \vec{u} \Big|_{\vec{Y}(t)} \right]$$

ADDED MASS

STOKES DRAG

$$\vec{X} \triangleq \left[ \vec{V} - \vec{u} \Big|_{\vec{Y}(t)} \right] - 6\pi a^2 \mu \int_0^t \frac{d\vec{X}/dz}{\sqrt{\pi \nu (t-z)}} dz + 6.46 \rho_f a^2 \sqrt{\nu} \cdot \vec{T}$$

BASSET HISTORY TERM

LIFT

$$m_p = \rho_p \cdot \frac{4}{3} \pi a^3 \quad \text{MASS OF THE PARTICLES} \quad \boxed{3}$$

$\searrow$   $a =$  PARTICLE RADIUS

$$m_f = \rho_f \cdot \frac{4}{3} \pi a^3 \quad \text{MASS OF FLUID DISPLACED BY THE PARTICLE}$$

$$\vec{V} \triangleq \vec{V}(t) \triangleq V_1 \vec{i} + V_2 \vec{j} \quad \text{PARTICLE VELOCITY}$$

$$\vec{u} \triangleq u_1 \vec{i} + u_2 \vec{j} \quad \text{FLUID VELOCITY}$$

$$\vec{Y}(t) \triangleq Y_1(t) \vec{i} + Y_2(t) \vec{j} \quad \text{PARTICLE POSITION}$$

$$\Gamma \triangleq \frac{[(\vec{u} - \vec{V}) \times (\vec{V} \times \vec{u})]}{\sqrt{|\vec{V} \times \vec{u}|}} \quad \text{with } \vec{V} \times \vec{u} \triangleq \text{VORTICITY}$$

Neglecting Basset and re-arranging:

$$\frac{d\vec{V}}{dt} = \frac{m_p - m_f}{m_p + \frac{1}{2} m_f} \vec{g} + \frac{m_f}{m_p + \frac{1}{2} m_f} \vec{u} \cdot \nabla \vec{u}$$

$$+ \frac{1}{2} \frac{m_f}{m_p + \frac{1}{2} m_f} \vec{V} \cdot \nabla \vec{u} - \frac{6\pi a \mu (\vec{V} - \vec{u})}{m_p + \frac{1}{2} m_f}$$

$$+ \frac{6,46 \rho_f a^2 \sqrt{w}}{m_p + \frac{1}{2} m_f} \cdot \Gamma$$

$$\textcircled{2} \frac{W^{(s)}}{Q} = \left( \frac{m_p - m_f}{6\pi a \mu} \cdot \frac{1}{U_0} \right) \cdot \frac{1}{\left( \frac{m_f}{6\pi a \mu} \cdot \frac{1}{U_0} \right)} =$$

$$= \frac{m_p - m_f}{m_f} = \frac{m_p + \frac{1}{2}m_f - \frac{3}{2}m_f}{m_f} = \frac{1}{R} - \frac{3}{2} \quad \boxed{\frac{W^{(s)}}{Q} = \left( \frac{1}{R} - \frac{3}{2} \right)}$$

For a bubble:

$$\rho_p \ll \rho_f \Rightarrow m_p \ll m_f \Rightarrow \vec{W}^{(s)} \approx - \frac{m_f \vec{g}}{6\pi a \mu}$$

Define  $\boxed{Q = |\vec{W}^{(s)*}| = \frac{|\vec{W}^{(s)}|}{U_0} = \frac{m_f \vec{g}}{6\pi a \mu} \cdot \frac{1}{U_0}}$

Similarly:  $\boxed{A \approx \frac{6\pi a \mu \cdot L}{\frac{1}{2}m_f} \equiv B}$

Therefore  $Q \equiv |\vec{W}^{(s)*}|$  and  $B \equiv A$  in the limit  $\rho_p \rightarrow 0$ .

Find:  $\textcircled{1} \frac{A}{B} = \left( \frac{6\pi a \mu \cdot L}{m_p + \frac{1}{2}m_f} \cdot \frac{1}{U_0} \right) \cdot \frac{1}{\left( \frac{6\pi a \mu \cdot L}{\frac{1}{2}m_f} \cdot \frac{1}{U_0} \right)}$

$$= \frac{1}{2} \frac{m_f}{m_p + \frac{1}{2}m_f} = \frac{1}{2} R \rightarrow \boxed{A = \frac{BR}{2}}$$

Define :

- \*  $0 < R \leq 0.4$  AEROSOL RANGE
- \*  $0.4 < R < 2$  TRANSITION RANGE
- \*  $R = 2$  BUBBLE RANGE

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•  $R \triangleq \frac{m_f}{m_p + \frac{1}{2} m_f}$

MASS RATIO

$\Rightarrow$  if  $\rho_p \gg \rho_f$  then  $R \rightarrow 0$

$\Rightarrow$  if  $\rho_p \ll \rho_f$  then  $R \rightarrow 2$

•  $\alpha \triangleq \frac{6\pi a \mu}{m_p + \frac{1}{2} m_f}$

INERTIA PARAMETER

$$\left[ \begin{aligned} \tau_p &= \frac{(\rho_p + \frac{1}{2} \rho_f) D_p^2}{18\mu} = \frac{(\rho_p + \frac{1}{2} \rho_f) \pi D_p^3}{18\mu} \cdot \frac{6}{\pi D_p} \\ &= \frac{m_p + \frac{1}{2} m_f}{3\pi \mu D_p} = \frac{m_p + \frac{1}{2} m_f}{6\pi a \mu} = \frac{1}{\alpha} !! \end{aligned} \right.$$

•  $\vec{W}^{(s)} \triangleq \frac{m_p - m_f}{6\pi a \mu} \vec{g}$

STOKES SETTLING VEL.

$\Rightarrow \vec{W}^{(s)} = \frac{m_p - m_f}{6\pi a \mu} \vec{g} \cdot \frac{m_p + \frac{1}{2} m_f}{m_p + \frac{1}{2} m_f}$

$= \frac{m_p - m_f}{m_p + \frac{1}{2} m_f} \vec{g} \cdot \frac{1}{\alpha}$

•  $Z \triangleq \frac{6.46 \rho_f a^2 \sqrt{N}}{m_p + \frac{1}{2} m_f} = \dots = \frac{1.5422}{a} \sqrt{\frac{\mu}{\rho_f}} \cdot R$

to get:

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$$\frac{d\vec{V}}{dt} = \alpha \vec{W}^{(s)} + R \left( \vec{u} \cdot \nabla \vec{u} - \frac{1}{2} \nabla \cdot \nabla \vec{u} \right) - \alpha (\vec{V} - \vec{u}) + \mathcal{L} \cdot \Gamma \quad (1)$$

Equation in non-dimensional form:

take  $\vec{V}^* = \vec{V} / U_0$

$$\vec{u}^* = \vec{u} / U_0$$

$$\vec{W}^{(s)*} = \vec{W}^s / U_0$$

$$\vec{X}^* = \vec{X} / L \quad + \quad A = \frac{\alpha L}{U_0}$$

$$\vec{Y}^* = \vec{Y} / L$$

$$t^* = t \cdot U_0 / L$$

substitute into (1) and re-arrange to obtain:

$$\frac{d\vec{V}^*}{dt^*} = A \left[ \vec{W}^{(s)*} + (\vec{u}^* - \vec{V}^*) \right] + R \left[ \vec{u}^* \cdot \nabla^* \vec{u}^* + \frac{1}{2} \nabla^* \cdot \nabla^* \vec{u}^* \right] + 0,727 \sqrt{A \cdot R} \cdot \frac{[(\vec{u}^* - \vec{V}^*) \times (\nabla^* \times \vec{u}^*)]}{\sqrt{|\nabla^* \times \vec{u}^*|}} \quad (2)$$

Dropping apex \*, Eq. (2) in scalar form reads as :

$$\frac{dV_i}{dt} = A(u_i - V_i) + R \left[ u_j \frac{\partial u_i}{\partial x_j} + \frac{1}{2} V_j \frac{\partial u_i}{\partial x_j} \right] + \frac{0.727}{\sqrt{|\vec{V} \times \vec{u}|}} \left[ \frac{AR [(\vec{u} - \vec{V}) \times (\vec{V} \times \vec{u})]}{|\vec{V} \times \vec{u}|} \right]_i$$

where  $i = 1, 2$ .

Note :

$$\begin{aligned}
 (\vec{u} - \vec{V}) \times (\vec{V} \times \vec{u}) &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 - V_1 & u_2 - V_2 & 0 \\ 0 & 0 & \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2} \end{vmatrix} = \\
 &= \vec{i} \left[ (u_2 - V_2) \left( \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2} \right) \right] \\
 &\quad - \vec{j} \left[ (u_1 - V_1) \left( \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2} \right) \right] = \\
 &= \vec{i} \left[ 2 \sin \gamma_1 \sin \gamma_2 (-\cos \gamma_1 \sin \gamma_2 - V_2) \right] + \vec{j} \left[ 2 \sin \gamma_1 \sin \gamma_2 (V_1 - \sin \gamma_1 \cos \gamma_2) \right]
 \end{aligned}$$

In summary, the equations to be integrated  $\boxed{7}$  in time for tracking particles in the cellular flow are:

$$\begin{aligned} \frac{1}{A} \frac{dV_1}{dt} + V_1 &= \sin Y_1 \cos Y_2 \\ &+ \frac{1}{2} \frac{R}{A} (V_1 \cos Y_1 \cos Y_2 - V_2 \sin Y_1 \sin Y_2) \\ &+ \frac{R}{A} \sin Y_1 \cos Y_2 \\ &+ 0,727 \sqrt{\frac{R}{A}} \cdot \frac{(V_2 - \cos Y_1 \sin Y_2)(-2 \sin Y_1 \sin Y_2)}{\sqrt{2 |\sin Y_1 \sin Y_2|}} \end{aligned}$$

$$\begin{aligned} \frac{1}{A} \frac{dV_2}{dt} + V_2 &= -\cos Y_1 \sin Y_2 \\ &+ \frac{1}{2} \frac{R}{A} (V_1 \sin Y_1 \sin Y_2 - V_2 \cos Y_1 \cos Y_2) \\ &+ \frac{R}{A} \sin Y_1 \cos Y_2 \\ &+ 0,727 \sqrt{\frac{R}{A}} \cdot \frac{(V_1 - \sin Y_1 \cos Y_2) \sin Y_1 \sin Y_2}{\sqrt{2 |\sin Y_1 \sin Y_2|}} \end{aligned}$$



### Possible projects :

1. Compute average settling/rising velocity  $\langle V_z \rangle$  and compare against Stokes velocity  $W^{(s)}$
2. Calculate equilibrium points and perform linear stability analysis  $\implies$
3. Compute the compressibility of the particle phase  $\implies$  Jacobian

Do this considering different values of the particle-to-fluid density ratio  $\rho_p/\rho_f$  and different sets of forces acting on the particles  
 ( I : M&R&F ; II : M&R&F + Added Mass ;  
 III : M&R&F + Lift + Added Mass )

# Technical details :

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## • INITIAL & BOUNDARY CONDITION

⇒ Initial particle position : random distr.

⇒ Initial particle velocity :

x equal to zero ( $V_1 = V_2 = 0 @ t=0$ )

x equal to the fluid velocity at the  
particle initial position

$$(V_i = u_i / Y_i(t)) @ t=0$$

⇒ Boundary condition : periodic

## • TIME INTEGRATION

⇒ Runge - Kutta (4<sup>th</sup> - order)

x subroutine available at

[www.nr.com](http://www.nr.com)

⇒ solve for the following system of 1<sup>st</sup>-order ODEs :

$$\left\{ \begin{aligned} \frac{dY_1(t)}{dt} &= V_1(t) \\ \frac{dY_2(t)}{dt} &= V_2(t) \\ \frac{dV_1(t)}{dt} &= A \cdot [-V_1 + \sin Y_1 \cos Y_2 + \dots] \\ \frac{dV_2(t)}{dt} &= A \cdot [-V_2 - \cos Y_1 \sin Y_2 + \dots] \end{aligned} \right.$$